MAJORIZING FUNCTIONS AND CONVERGENCE OF THE GAUSS–NEWTON METHOD FOR CONVEX COMPOSITE OPTIMIZATION

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Abstract. We introduce a notion of quasi regularity for points with respect to the inclusion $F(x) \in C$, where $F$ is a nonlinear Fréchet differentiable function from $\mathbb{R}^v$ to $\mathbb{R}^m$. When $C$ is the set of minimum points of a convex real-valued function $h$ on $\mathbb{R}^m$ and $F'$ satisfies the $L$-average Lipschitz condition of Wang, we use the majorizing function technique to establish the semilocal linear/quadratic convergence of sequences generated by the Gauss–Newton method (with quasi-regular initial points) for the convex composite function $h \circ F$. Results are new even when the initial point is regular and $F'$ is Lipschitz.

Key words. the Gauss–Newton method, convex composite optimization, majorizing function, convergence

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1. Introduction. The convex composite optimization to be considered is as follows:

\[(1.1) \quad \min_{x \in \mathbb{R}^v} f(x) := h(F(x)),\]

where $h$ is a real-valued convex function on $\mathbb{R}^m$ and $F$ is a nonlinear Fréchet differentiable map from $\mathbb{R}^v$ to $\mathbb{R}^m$ (with norm $\| \cdot \|$). We assume throughout that $h$ attains its minimum $h_{\text{min}}$.

This problem has recently received a great deal of attention. As observed by Burke and Ferris in their seminal paper [4], a wide variety of its applications can be found throughout the mathematical programming literature, especially in convex inclusion, minimax problems, penalization methods, and goal programming (see also [2, 6, 7, 15, 22]). The study of (1.1) provides not only a unifying framework for the development and analysis of algorithms for solutions but also a convenient tool for the study of first- and second-order optimality conditions in constrained optimization [3, 5, 7, 22]. As in [4, 13], the study of (1.1) naturally relates to the convex inclusion problem

\[(1.2) \quad F(x) \in C,\]

where

\[(1.3) \quad C := \text{argmin } h,\]

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the set of all minimum points of \( h \). Of course, it is meaningful to study (1.2) in its own right for a general closed convex set (cf. [14, 16]). In section 3, we introduce a new notion of quasi regularity for \( x_0 \in \mathbb{R}^n \) with respect to the inclusion (1.2). This new notion covers the case of regularity studied by Burke and Ferris [4] as well as the case when \( F'(x_0) - C \) is surjective, employed by Robinson [18]. More importantly, we introduce notions of the quasi-regular radius \( r_{x_0} \) and of the quasi-regular bound function \( \beta_{x_0} \) attached to each quasi-regular point \( x_0 \). For the general case this pair \((r_{x_0}, \beta_{x_0})\) together with a suitable Lipschitz-type assumption on \( F' \) enables us to address the issue of convergence of Gauss–Newton sequences provided by the following well-known algorithm (cf. [4, 10, 13, 31]).

**Algorithm A \((\eta, \Delta, x_0)\).** Let \( \eta \in [1, +\infty) \), \( \Delta \in (0, +\infty) \), and for each \( x \in \mathbb{R}^n \) define \( D_\Delta(x) \) by

\[
D_\Delta(x) = \{ d \in \mathbb{R}^n : \|d\| \leq \Delta, h(F(x) + F'(x)d) \leq h(F(x) + F'(x)d') \forall d' \in \mathbb{R}^n \text{ with } \|d'\| \leq \Delta \}.
\]

Let \( x_0 \in \mathbb{R}^n \) be given. For \( k = 0, 1, \ldots \), having \( x_0, x_1, \ldots, x_k \), determine \( x_{k+1} \) as follows.

If \( 0 \in D_\Delta(x_k) \), then stop; if \( 0 \notin D_\Delta(x_k) \), choose \( d_k \) such that \( d_k \in D_\Delta(x_k) \) and

\[
\|d_k\| \leq \eta d(0, D_\Delta(x_k)),
\]

and set \( x_{k+1} = x_k + d_k \). Here \( d(x, W) \) denotes the distance from \( x \) to \( W \) in the finite-dimensional Banach space containing \( W \).

Note that \( D_\Delta(x) \) is nonempty and is the solution set of the following convex optimization problem:

\[
\min_{d \in \mathbb{R}^n, \|d\| \leq \Delta} h(F(x) + F'(x)d),
\]

which can be solved by standard methods such as the subgradient method, the cutting plane method, the bundle method, etc. (cf. [9]).

If the initial point \( x_0 \) is a quasi-regular point with \((r_{x_0}, \beta_{x_0})\) and if \( F' \) satisfies a Lipschitz-type condition (introduced by Wang [28]) with an absolutely continuous function \( L \) satisfying a suitable property in relation to \((r_{x_0}, \beta_{x_0})\), our main results presented in section 4 show that the Gauss–Newton sequence \( \{x_n\} \) provided by Algorithm A \((\eta, \Delta, x_0)\) converges at a quadratic rate to some \( x^* \) with \( F(x^*) \in C \) (in particular, \( x^* \) solves (1.1)). Even in the special case when \( x_0 \) is regular and \( F' \) is Lipschitz, the advantage of allowing \( \beta_{x_0} \) and \( L \) to be functions (rather than constants) provides results which are new even for the above special case. Examples are given in section 6 to show there are situations where our results are applicable but not the earlier results in the literature; in particular, Example 6.1 is a simple example to demonstrate a quasi-regular point which is not regular. We shall show that the Gauss–Newton sequence \( \{x_n\} \) is “majorized” by the corresponding numerical sequence \( \{t_n\} \) generated by the classical Newton method with initial point \( t_0 = 0 \) for a “majorizing” function of the following type (again introduced by Wang [28]):

\[
\phi_\alpha(t) = \xi - t + \alpha \int_0^t L(u)(t - u) \, du \text{ for each } t \geq 0,
\]

where \( \xi, \alpha \) are positive constants and \( L \) is a positive-valued increasing (more precisely, nondecreasing) absolutely continuous function on \([0, +\infty)\). In the case when \( L \) is a
constant function, (1.7) reduces to
\[
\phi_\alpha(t) = \xi - t + \frac{\alpha L(t^2)}{2} \quad \text{for each } t \geq 0,
\]
the majorizing function used by Kantorovich [11] and by Kantorovich and Akilov [12]. In the case when
\[
L(u) = \frac{2\gamma}{(1 - \gamma u)^3},
\]
expression (1.7) reduces to
\[
\phi_\alpha(t) = \xi - t + \frac{\alpha \gamma t^2}{1 - \gamma t},
\]
the majorizing function that Wang made use of in his work [28] on approximate zeros of Smale (cf. [26]). Motivated by this and as an application of our results in section 4, we provide a sufficient condition ensuring that a point \(x_0 \in \mathbb{R}^v\) will be an "approximate solution" of (1.1) in the sense that the Gauss–Newton sequence \(\{x_n\}\) generated by Algorithm A \((\eta, \Delta, x_0)\) converges to a solution of (1.1) and satisfies the condition
\[
\|x_{n+1} - x_n\| \leq \left(\frac{1}{2}\right)^{2^{n-1}} \|x_n - x_{n-1}\| \quad \text{for each } n = 1, 2, \ldots
\]
(the last condition was used by Smale [26] in his study of approximate zeros for Newton’s method).

2. Preliminaries. Let \(B(x, r)\) stand for the open ball in \(\mathbb{R}^v\) or \(\mathbb{R}^m\) with center \(x\) and radius \(r\), while the corresponding closed ball is denoted by \(\overline{B}(x, r)\). Let \(W\) be a closed convex subset of \(\mathbb{R}^v\) or \(\mathbb{R}^m\). The negative polar of \(W\) is denoted by \(W^\ominus\) and defined by
\[
W^\ominus = \{z : \langle z, w \rangle \leq 0 \text{ for each } w \in W\}.
\]
Let \(L\) be a positive-valued increasing absolutely continuous function on \([0, +\infty)\), and let \(\alpha > 0\). Let \(r_\alpha > 0\) and \(b_\alpha > 0\) such that
\[
\alpha \int_0^{r_\alpha} L(u) \, du = 1 \quad \text{and} \quad b_\alpha = \alpha \int_0^{r_\alpha} L(u) u \, du
\]
(thus \(b_\alpha < r_\alpha\)). Let \(\xi \geq 0\), and define
\[
\phi_\alpha(t) = \xi - t + \alpha \int_0^t L(u)(t - u) \, du \quad \text{for each } t \geq 0.
\]
Thus
\[
\phi_\alpha'(t) = -1 + \alpha \int_0^t L(u) \, du, \quad \phi_\alpha''(t) = \alpha L(t) \quad \text{for each } t \geq 0,
\]
and \(\phi_\alpha''(t)\) exists almost everywhere thanks to the assumption that \(L\) is absolutely continuous. Let \(t_{\alpha,n}\) denote the sequence generated by Newton’s method for \(\phi_\alpha\) with initial point \(t_{\alpha,0} = 0:\)
\[
t_{\alpha,n+1} = t_{\alpha,n} - \phi_\alpha'(t_{\alpha,n})^{-1} \phi_\alpha(t_{\alpha,n}) \quad \text{for each } n = 0, 1, \ldots
\]
In particular, by (2.2) and (2.3),

\begin{equation}
(2.5) \quad t_{\alpha,1} = \xi.
\end{equation}

Below we list a series of useful lemmas for our purpose. They are either known or can be verified easily by elementary methods (such as by differential calculus). In particular, Lemma 2.3 and Lemma 2.1(i) are taken from [28], while Lemma 2.1(ii) and (iii) are well known. Here we shall give a proof of Lemma 2.4 as an illustration.

**LEMMA 2.1.** Suppose that $0 < \xi \leq b_\alpha$. Then $b_\alpha < r_\alpha$ and the following assertions hold:

(i) $\phi_\alpha$ is strictly decreasing on $[0, r_\alpha]$ and strictly increasing on $[r_\alpha, +\infty)$ with

\begin{equation}
(2.6) \quad \phi_\alpha(\xi) > 0, \quad \phi_\alpha(r_\alpha) = \xi - b_\alpha \leq 0, \quad \phi_\alpha(+\infty) \geq \xi > 0.
\end{equation}

Moreover, if $\xi < b_\alpha$, $\phi_\alpha$ has two zeros, denoted respectively by $r_\alpha^*$ and $r_\alpha^{**}$, such that

\begin{equation}
(2.7) \quad \xi < r_\alpha^* < \frac{r_\alpha}{b_\alpha} \xi < r_\alpha < r_\alpha^{**},
\end{equation}

and if $\xi = b_\alpha$, then $\phi_\alpha$ has a unique zero $r_\alpha^*$ in $(\xi, +\infty)$ (in fact, $r_\alpha^* = r_\alpha$).

(ii) $\{t_{\alpha,n}\}$ is strictly monotonically increasing and converges to $r_\alpha^*$.

(iii) The convergence of $\{t_{\alpha,n}\}$ is of quadratic rate if $\xi < b_\alpha$, and linear if $\xi = b_\alpha$.

**LEMMA 2.2.** Let $r_\alpha$, $b_\alpha$, and $\phi_\alpha$ be defined by (2.1) and (2.2). Let $\alpha' > \alpha$ with the corresponding $\phi_{\alpha'}$. Then the following assertions hold:

(i) The functions $\alpha \mapsto r_\alpha$ and $\alpha \mapsto b_\alpha$ are strictly decreasing on $(0, +\infty)$.

(ii) $\phi_\alpha < \phi_{\alpha'}$ on $(0, +\infty)$.

(iii) The function $\alpha \mapsto r_\alpha^*$ is strictly increasing on the interval $I(\xi)$, where $I(\xi)$ denotes the set of all $\alpha > 0$ such that $\xi \leq b_\alpha$.

**LEMMA 2.3.** Let $0 \leq c < +\infty$. Define

\begin{equation}
(2.8) \quad \chi(t) = \frac{1}{12} \int_0^t L(c + u)(t - u) \, du \quad \text{for each } 0 \leq t < +\infty.
\end{equation}

Then $\chi$ is increasing on $[0, +\infty)$.

**LEMMA 2.4.** Define

$$
\omega_\alpha(t) = \phi'_\alpha(t)^{-1} \phi_\alpha(t), \quad \text{for each } t \in [0, r_\alpha^*].
$$

Suppose that $0 < \xi \leq b_\alpha$. Then $\omega_\alpha$ is increasing on $[0, r_\alpha^*]$.

**Proof.** Since

$$
\omega'_\alpha(t) = \frac{\phi'_\alpha(t)^2 - \phi_\alpha(t)\phi''_\alpha(t)}{\phi'_\alpha(t)^2} \quad \text{for each } t \in [0, r_\alpha^*],
$$

it suffices to show that

$$
\zeta_\alpha(t) := \phi''_\alpha(t)^2 - \phi_\alpha(t)\phi''_\alpha(t) \geq 0 \quad \text{for each } t \in [0, r_\alpha^*].
$$

Since $\zeta_\alpha(r_\alpha^*) = \phi''_\alpha(r_\alpha^*)^2 \geq 0$, it remains to show that $\zeta_\alpha$ is decreasing on $[0, r_\alpha^*]$. To do this, note that by (2.3), $\zeta_\alpha$ is absolutely continuous, and so the derivative of $\zeta_\alpha$ exists almost everywhere on $[0, r_\alpha^*]$ with

$$
\zeta'_\alpha(t) = \phi'_\alpha(t)\phi''_\alpha(t) - \phi_\alpha(t)\phi''_\alpha(t) \leq 0 \quad \text{for a.e. } t \in [0, r_\alpha^*],
$$
because $\phi'_\alpha \leq 0$ while $\phi'_\alpha$, $\phi''_\alpha \geq 0$ almost everywhere on $[0,r^*_\alpha)$. Therefore, $\zeta_\alpha$ is decreasing on $[0,r^*_\alpha)$, and the proof is complete.

The following conditions were introduced by Wang in [28] but using the terminologies of “the center Lipschitz condition with the $L$ average” and “the center Lipschitz condition in the inscribed sphere with the $L$ average,” respectively, for (a) and (b).

**Definition 2.5.** Let $Y$ be a Banach space and let $x_0 \in \mathbb{R}^n$. Let $G$ be a mapping from $\mathbb{R}^n$ to $Y$. Then $G$ is said to satisfy

(a) the weak $L$-average Lipschitz condition on $B(x_0,r)$ if

\begin{equation}
(3.1) \quad \|G(x) - G(x_0)\| \leq \int_0^{\|x-x_0\|} L(u) \, du \quad \text{for each } x \in B(x_0,r);
\end{equation}

(b) the $L$-average Lipschitz condition on $B(x_0,r)$ if

\begin{equation}
(3.2) \quad \|G(x) - G(x')\| \leq \int_{\|x'-x_0\|}^{\|x-x'\|+\|x'-x_0\|} L(u) \, du \quad \text{for all } x, x' \in B(x_0,r)
\end{equation}

with $\|x-x'\| + \|x'-x_0\| \leq r$.

3. Regularities. Let $C$ be a closed convex set in $\mathbb{R}^m$. Consider the inclusion

\begin{equation}
F(x) \in C.
\end{equation}

Let $x \in \mathbb{R}^n$ and

\begin{equation}
(3.3) \quad D(x) = \{d \in \mathbb{R}^n : F(x) + F'(x)d \in C\}.
\end{equation}

**Remark 3.1.** In the case when $C$ is the set of all minimum points of $h$ and if there exists $d_0 \in \mathbb{R}^n$ with $\|d_0\| \leq \Delta$ such that $d_0 \in D(x)$, then $d_0 \in D\Delta(x)$, and for each $d \in \mathbb{R}^n$ with $\|d\| \leq \Delta$ one has

\begin{equation}
(3.4) \quad d \in D\Delta(x) \iff d \in D(x) \iff d \in D\infty(x).
\end{equation}

**Remark 3.2.** The set $D(x)$ defined in (3.2) can be viewed as the solution set of the following “linearized” problem associated with (3.1):

\begin{equation}
(3.5) \quad (P_x) : \quad F(x) + F'(x) d \in C.
\end{equation}

Thus $\beta(\|x-x_0\|)$ in (3.5) is an “error bound” in determining how far the origin is away from the solution set of $(P_x)$.

**Definition 3.1.** A point $x_0 \in \mathbb{R}^n$ is called a quasi-regular point of the inclusion (3.1) if there exist $r \in (0,\infty)$ and an increasing positive-valued function $\beta$ on $[0,r)$ such that

\begin{equation}
(3.6) \quad \beta_{x_0}(t) = \inf\{\beta(t) : \beta \in B_{r_{x_0}}(x_0)\} \quad \text{for each } t \in [0,r_{x_0}).
\end{equation}
Note that each $\beta \in \mathcal{B}_t(x_0)$ with $\lim_{t \to r^-} \beta(t) < +\infty$ can be extended to an element of $\mathcal{B}_{x_0}(x_0)$. From this we can verify that

$$\beta_{x_0}(t) = \inf\{\beta(t) : \beta \in \mathcal{B}_t(x_0)\} \text{ for each } t \in [0, r).$$

We call $r_{x_0}$ and $\beta_{x_0}$ respectively the quasi-regular radius and the quasi-regular bound function of the quasi-regular point $x_0$.

**Definition 3.2.** A point $x_0 \in \mathbb{R}^n$ is a regular point of the inclusion (3.1) if

$$\ker(F'(x_0)^T) \cap (C - F(x_0)) = \{0\}.$$ 

The notion of regularity relates to some other notions of regularity that can be found in the papers [1, 3, 20, 21, 25], which have played an important role in the study of nonsmooth optimizations. Some equivalent conditions on the regular points for (3.1) are given in [4]. In the following proposition the existence of constants $r$ and $\beta$ is due to Burke and Ferris [4], and the second assertion then follows from a remark after Definition 3.1.

**Proposition 3.3.** Let $x_0$ be a regular point of (3.1). Then there are constants $r > 0$ and $\beta > 0$ such that (3.5) holds for $r$ and $\beta(.) = \beta$; consequently, $x_0$ is a quasi-regular point with the quasi-regular radius $r_{x_0} \geq r$ and the quasi-regular bound function $\beta_{x_0} \leq \beta$ on $[0, r]$.

Another important link of the present study relates to Robinson’s condition [18, 19] that the convex process $d \mapsto F'(x)d - C$ is onto $\mathbb{R}^m$. To see this, let us first recall the concept of convex process, which was introduced by Rockafeller [23, 24] for convexity problems (see also Robinson [19]).

**Definition 3.4.** A set-valued mapping $T : \mathbb{R}^v \to 2^{\mathbb{R}^m}$ is called a convex process from $\mathbb{R}^v$ to $\mathbb{R}^m$ if it satisfies

(a) $T(x + y) \supseteq Tx + Ty$ for all $x, y \in \mathbb{R}^v$;
(b) $T\lambda x = \lambda Tx$ for all $\lambda > 0$, $x \in \mathbb{R}^v$;
(c) $0 \in T0$.

Thus $T : \mathbb{R}^v \to 2^{\mathbb{R}^m}$ is a convex process if and only if its graph $Gr(T)$ is a convex cone in $\mathbb{R}^v \times \mathbb{R}^m$. As usual, the domain, range, and inverse of a convex process $T$ are respectively denoted by $D(T)$, $R(T)$, $T^{-1}$; i.e.,

$$D(T) = \{x \in \mathbb{R}^v : Tx \neq 0\},$$

$$R(T) = \cup\{Tx : x \in D(T)\},$$

$$T^{-1}y = \{x \in \mathbb{R}^v : y \in Tx\}.$$}

Obviously $T^{-1}$ is a convex process from $\mathbb{R}^m$ to $\mathbb{R}^v$. Furthermore, for a set $A$ in an $\mathbb{R}^v$ or $\mathbb{R}^m$, it would be convenient to use the notation $\|A\|$ to denote its distance to the origin, that is,

$$\|A\| = \inf\{\|a\| : a \in A\}.$$ 

**Definition 3.5.** Suppose that $T$ is a convex process. The norm of $T$ is defined by

$$\|T\| = \sup\{\|Tx\| : x \in D(T), \|x\| \leq 1\}.$$ 

If $\|T\| < +\infty$, we say that the convex process $T$ is normed.
For two convex processes $T$ and $S$ from $\mathbb{R}^v$ to $\mathbb{R}^m$, the addition and multiplication are defined respectively as follows:

$$(T + S)(x) = Tx + Sx \quad \text{for each } x \in \mathbb{R}^v,$$

$$(\lambda T)(x) = \lambda (Tx) \quad \text{for each } x \in \mathbb{R}^v \text{ and } \lambda \in \mathbb{R}.$$  

Let $C$ be a closed convex set in $\mathbb{R}^m$ and let $x \in \mathbb{R}^v$. We define $T_x$ by

$$(3.10) \quad T_x d = F'(x) d - C \quad \text{for each } d \in \mathbb{R}^v.$$  

Then its inverse is

$$(3.11) \quad T_x^{-1} y = \{d \in \mathbb{R}^v : F'(x) d \in y + C\} \quad \text{for each } y \in \mathbb{R}^m.$$  

Note that $T_x$ is a convex process in the case when $C$ is a cone. Note also that $D(T_x) = \mathbb{R}^v$ for each $x \in \mathbb{R}^v$ and $D(T_x^{-1}) = \mathbb{R}^m$ if $x_0 \in \mathbb{R}^v$ is such that the following condition of Robinson is satisfied:

$$(3.12) \quad T_{x_0} \text{ carries } \mathbb{R}^v \text{ onto } \mathbb{R}^m.$$  

Proposition 3.7 below shows that the condition of Robinson (3.12) implies that $x_0$ is a regular point of (3.1), and an estimate of the quasi-regular bound function is provided. For its proof we need the following lemma, which is known in [18].

**Lemma 3.6.** Let $C$ be a closed convex cone in $\mathbb{R}^m$, and let $x_0 \in \mathbb{R}^v$ be such that the condition of Robinson (3.12) is satisfied. Then the following assertions hold:

(i) $T_{x_0}^{-1}$ is normed.

(ii) If $S$ is a linear transformation from $\mathbb{R}^v$ to $\mathbb{R}^m$ such that $\|T_{x_0}^{-1}\|\|S\| < 1$, then the convex process $\tilde{T}$ defined by

$$\tilde{T} = T_{x_0} + S$$

carries $\mathbb{R}^v$ onto $\mathbb{R}^m$. Furthermore, $\tilde{T}^{-1}$ is normed and

$$\|\tilde{T}^{-1}\| \leq \frac{\|T_{x_0}^{-1}\|}{1 - \|T_{x_0}^{-1}\|\|S\|}.$$  

**Proposition 3.7.** Let $x_0 \in \mathbb{R}^v$, and let $T_{x_0}$ be defined as in (3.10). Suppose that the condition of Robinson (3.12) is satisfied. Then the following assertions hold:

(i) $x_0$ is a regular point of (3.1).

(ii) Suppose further that $C$ is a closed convex cone in $\mathbb{R}^m$ and that $F'$ satisfies the weak $L$-average Lipschitz condition on $\mathcal{B}(x_0, r)$ for some $r > 0$. Let $\beta_0 = \|T_{x_0}^{-1}\|$ and let $r_{\beta_0}$ be defined by

$$(3.13) \quad \beta_0 \int_0^{r_{\beta_0}} L(u) \ du = 1$$

(cf. (2.1)). Then the quasi-regular radius $r_{x_0}$ and the quasi-regular bound function $\beta_{x_0}$ satisfy $r_{x_0} \geq \min\{r, r_{\beta_0}\}$ and

$$(3.14) \quad \beta_{x_0}(t) \leq \frac{\beta_0}{1 - \beta_0 \int_0^t L(u) \ du} \quad \text{for each } t \text{ with } 0 \leq t < \min\{r, r_{\beta_0}\}.$$
Proof. Suppose that the condition (3.12) is satisfied, and let $y$ belong to the set of the intersection in (3.8). Then, in view of the definition of $T_{x_0}$, there exist $u \in \mathbb{R}^v$ and $c \in C$ such that $-y - F(x_0) = F'(x_0)u - c$. Hence, by (3.8),

$$
\langle y, F'(x_0)u \rangle = \langle F'(x_0)^T y, u \rangle = 0 \quad \text{and} \quad \langle y, c - F(x_0) \rangle \leq 0.
$$

It follows that

$$
\langle y, y \rangle = \langle y, c - F(x_0) - F'(x_0)u \rangle = \langle y, c - F(x_0) \rangle \leq 0
$$

and hence $y = 0$. This shows that (3.8) holds, and so $x_0$ is a regular point of the inclusion (3.1).

Now let $r > 0$ and suppose that $F'$ satisfies the weak $L$-average Lipschitz condition on $B(x_0, r)$. Let $x \in \mathbb{R}^v$ such that $\|x - x_0\| < \min\{r, r_{\beta_0}\}$. Then

$$
\|F'(x) - F'(x_0)\| \leq \int_0^{\|x-x_0\|} L(u) \, du < \int_0^{r_{\beta_0}} L(u) \, du;
$$

hence, by (3.13),

$$
\|T_{x_0}^{-1}\| \|F'(x) - F'(x_0)\| < \|T_{x_0}^{-1}\| \int_0^{r_{\beta_0}} L(u) \, du = 1.
$$

This with Lemma 3.6 implies that the convex process defined by

$$
T_x d = F'(x) d - C = T_{x_0} d + [F'(x) - F'(x_0)] d \quad \text{for each} \ d \in \mathbb{R}^v
$$

carries $\mathbb{R}^v$ onto $\mathbb{R}^m$ and

$$
\|T_x^{-1}\| \leq \frac{\|T_{x_0}^{-1}\|}{1 - \|T_{x_0}^{-1}\| \|F'(x) - F'(x_0)\|} \leq \frac{\|T_{x_0}^{-1}\|}{1 - \|T_{x_0}^{-1}\| \int_0^{\|x-x_0\|} L(u) \, du}.
$$

Since $T_x$ is surjective, we have that $D(x)$ is nonempty; in particular, for each $c \in C$,

$$
T_x^{-1}(c - F(x)) \subseteq D(x). \tag{3.18}
$$

To see this, let $d \in T_x^{-1}(c - F(x))$. Then, by (3.11), one has that $F'(x) d \in c - F(x) + C \subseteq C - F(x)$, and so $F(x) + F'(x) d \in C$, that is, $d \in D(x)$. Hence (3.18) is true. Consequently,

$$
d(0, D(x)) \leq \|T_x^{-1}(c - F(x))\| \leq \|T_x^{-1}\||c - F(x)||.
$$

Since this is valid for each $c \in C$, it is seen that

$$
d(0, D(x)) \leq \|T_x^{-1}\|d(F(x), C).
$$

Combining this with (3.17) and (3.6) gives the desired result (3.14), and the proof is complete. □

4. Convergence criterion. We assume throughout the remainder of this paper that $C$ is the set of all minimum points of $h$. Let $x_0 \in \mathbb{R}^v$ be a quasi-regular point of the inclusion (3.1) with the quasi-regular radius $r_{x_0}$ and the quasi-regular bound function $\beta_{x_0}$. Let $\eta \in [1, +\infty)$ and let

$$
\xi := \eta \beta_{x_0}(0) d(F(x_0), C). \tag{4.1}
$$
For all \( r \in (0, r_{x_0}] \), we define

\[
\alpha_0(r) := \sup \left\{ \frac{\eta \beta_x(t)}{\eta \beta_{x_0}(t) \int_0^t L(u) \, du + 1} : \xi \leq t < r \right\},
\]

with the usual convention that \( \sup \emptyset = -\infty \).

**Theorem 4.1.** Let \( \eta \in [1, \infty) \) and \( \Delta \in (0, \infty] \). Let \( x_0 \in \mathbb{R}^v \) be a quasi-regular point of the inclusion (3.1) with the quasi-regular radius \( r_{x_0} \) and the quasi-regular bound function \( \beta_{x_0} \). Let \( \xi > 0, 0 < r \leq r_{x_0}, \) and \( \alpha_0(r) \) be as described above. Let \( \alpha \geq \alpha_0(r) \) be a positive constant and let \( b_\alpha, r_\alpha \) be defined by (2.1). Let \( r^*_\alpha \) denote the smaller zero of the function \( \phi_\alpha \) defined by (2.2). Suppose that \( F' \) satisfies the \( L \)-average Lipschitz condition on \( B(x_0, r^*_\alpha) \), and that

(4.3) \( \xi \leq \min \{ b_\alpha, \Delta \} \) and \( r^*_\alpha \leq r \)

(for example, (4.3) is satisfied if\( \xi \leq \min \{ b_\alpha, \Delta \} \) holds). Let \{\( x_n \}\} denote the sequence generated by Algorithm A\( (\eta, \Delta, x_0) \). Then, \{\( x_n \}\} converges to some \( x^* \) such that \( F(x^*) \in C \), and the following assertions hold for each \( n = 1, 2, \ldots \):

(4.5) \( \|x_n - x_{n-1}\| \leq t_{\alpha,n} - t_{\alpha,n-1} \),

(4.6) \( \|x_{n+1} - x_n\| \leq (t_{\alpha,n+1} - t_{\alpha,n}) \left( \frac{\|x_n - x_{n-1}\|}{t_{\alpha,n} - t_{\alpha,n-1}} \right)^2 \),

(4.7) \( F(x_n) + F'(x_n)(x_{n+1} - x_n) \in C \),

and

(4.8) \( \|x_{n-1} - x^*\| \leq r^*_\alpha - t_{\alpha,n-1} \).

**Proof.** By (2.7) and (4.4),

\( r^*_\alpha \leq \frac{r_n}{b_\alpha} \xi \leq r \).

Hence (4.4) \( \Rightarrow \) (4.3). Thus it suffices to prove the theorem for the case when (4.3) is assumed. By (4.3), (2.5), and Lemma 2.1, one has that, for each \( n \)

(4.10) \( \xi \leq t_{\alpha,n} < r^*_\alpha \leq r \leq r_{x_0} \).

By the quasi regularity assumption, it follows that

(4.11) \( D(x) \neq \emptyset \) and \( d(0, D(x)) \leq \beta_{x_0}(\|x - x_0\|) d(F(x), C) \)

for each \( x \in B(x_0, r) \).

Let \( k \geq 1 \). We use \( \overline{1,k} \) to denote the set of all integers \( n \) satisfying \( 1 \leq n \leq k \). Below we will verify the following implication:

(4.12) \( \) (4.5) holds for all \( n \in \overline{1,k} \), and (4.7) holds for \( n = k - 1 \)

\( \Rightarrow \) (4.6) and (4.7) hold for \( n = k \).
To do this, suppose that (4.5) holds for each \( n \in \overline{1,k} \), and set

\[
x_k^\tau = \tau x_k + (1 - \tau)x_{k-1} \quad \text{for each } \tau \in [0,1].
\]

Note that

\[
\|x_k - x_0\| \leq \sum_{i=1}^{k} \|x_i - x_{i-1}\| \leq \sum_{i=1}^{k} (t_{\alpha,i} - t_{\alpha,i-1}) = t_{\alpha,k}
\]

and

\[
\|x_{k-1} - x_0\| \leq t_{\alpha,k-1} \leq t_{\alpha,k}.
\]

It follows from (4.13) and (4.10) that \( x_k^\tau \in B(x_0, r_{\alpha}^*) \subseteq B(x_0, r) \) for each \( \tau \in [0,1] \). Hence (4.11) holds for \( x = x_k \), namely,

\[
\mathcal{D}(x_k) \neq \emptyset \quad \text{and} \quad d(0, \mathcal{D}(x_k)) \leq \beta_{x_0}(\|x_k - x_0\|) d(F(x_k), C).
\]

We claim that

\[
\eta d(0, \mathcal{D}(x_k)) \leq (t_{\alpha,k+1} - t_{\alpha,k}) \left( \frac{\|x_k - x_{k-1}\|}{t_{\alpha,k} - t_{\alpha,k-1}} \right)^2 \leq t_{\alpha,k+1} - t_{\alpha,k}
\]

(the second inequality needs no proof by the assumption of (4.12)). To show the first inequality, using (4.7) for \( n = k - 1 \) and the fact that \( F' \) satisfies an \( L \)-average Lipschitz condition on \( B(x_0, r_{\alpha}^*) \), together with the elementary identity

\[
\int_0^1 \int_A^{A + \tau B} L(u) \, du \, d\tau = \int_0^B L(A + u)(1 - \frac{u}{B}) \, du \quad \text{for all } A, B > 0,
\]

we have by (4.16) that

\[
\eta d(0, \mathcal{D}(x_k)) \leq \eta \beta_{x_0}(\|x_k - x_0\|) d(F(x_k), C)
\leq \eta \beta_{x_0}(\|x_k - x_0\|) \|F(x_k) - F(x_{k-1}) - F'(x_{k-1})(x_k - x_{k-1})\|
\leq \eta \beta_{x_0}(\|x_k - x_0\|) \left( \int_0^1 (F'(x_k^\tau) - F'(x_{k-1}))(x_k - x_{k-1}) \, d\tau \right)
\leq \eta \beta_{x_0}(\|x_k - x_0\|) \left( \int_0^1 \left( \int_{\|x_k - x_k-1\|}^{\|x_k - x_k-1\| + \|x_k-1 - x_0\|} L(u) \, du \right) \right)
\times \|x_k - x_{k-1}\| \, d\tau
= \eta \beta_{x_0}(\|x_k - x_0\|) \times \left( \int_0^{\|x_k - x_{k-1}\|} L(\|x_{k-1} - x_0\| + u)(\|x_k - x_{k-1}\| - u) \, du \right)
\leq \eta \beta_{x_0}(t_{\alpha,k}) \left( \int_0^{\|x_k - x_{k-1}\|} L(t_{\alpha,k-1} + u)(\|x_k - x_{k-1}\| - u) \, du \right),
\]
Similarly by (2.2), (2.3), (2.4), and (4.18), we have
\[ (4.19) \]
so (4.17) implies that
\[ d_{\alpha} \geq (0,1) \]
\[ \phi_{\alpha}(t_{\alpha,k},0) = \phi_{\alpha}(t_{\alpha,k}) - \phi_{\alpha}(t_{\alpha,k-1}) - \phi'_{\alpha}(t_{\alpha,k-1})(t_{\alpha,k} - t_{\alpha,k-1}) \]

\[ (4.20) \]
and it follows from the earlier estimate that
\[ \eta d(0, D(x_k)) \leq \eta \beta_{x_0}(t_{\alpha,k}) \left( \int_{0}^{t_{\alpha,k} - t_{\alpha,k-1}} L(t_{\alpha,k-1} + u)(t_{\alpha,k} - t_{\alpha,k-1} - u) du \right) \]

(4.19) \[ \times \left( \frac{\|x_k - x_{k-1}\|}{t_{\alpha,k} - t_{\alpha,k-1}} \right)^2. \]

Similarly by (2.2), (2.3), (2.4), and (4.18), we have
\[ \phi_{\alpha}(t_{\alpha,k}) = \phi_{\alpha}(t_{\alpha,k}) - \phi_{\alpha}(t_{\alpha,k-1}) - \phi'_{\alpha}(t_{\alpha,k-1})(t_{\alpha,k} - t_{\alpha,k-1}) \]

\[ (4.20) \]
\[ = \alpha \int_{0}^{t_{\alpha,k} - t_{\alpha,k-1}} L(t_{\alpha,k-1} + u)(t_{\alpha,k} - t_{\alpha,k-1} - u) du. \]

On the other hand, by (4.10) and (4.2),
\[ \frac{\eta \beta_{x_0}(t_{\alpha,k})}{\alpha_0(r)} \leq \left( 1 - \alpha_0(r) \int_{0}^{t_{\alpha,k}} L(u) du \right)^{-1}. \]

Since \( \alpha \geq \alpha_0(r) \) and by (2.3), it follows that
\[ (4.21) \]
\[ \frac{\eta \beta_{x_0}(t_{\alpha,k})}{\alpha} \leq \left( 1 - \alpha \int_{0}^{t_{\alpha,k}} L(u) du \right)^{-1} = -\left( \phi'_{\alpha}(t_{\alpha,k}) \right)^{-1}. \]

Combining (4.19)–(4.21) together with (2.4), the first inequality in (4.17) is seen to hold. Moreover, by Lemma 2.4 and (4.3), we have
\[ t_{\alpha,k+1} - t_{\alpha,k} = -\phi'_{\alpha}(t_{\alpha,k})^{-1} \phi_{\alpha}(t_{\alpha,k}) \leq -\phi'_{\alpha}(t_{\alpha,0})^{-1} \phi_{\alpha}(t_{\alpha,0}) = \xi \leq \Delta, \]
so (4.17) implies that \( d(0, D(x_k)) \leq \Delta \). Hence there exists \( d_0 \in \mathbb{R}^n \) with \( \|d_0\| \leq \Delta \) such that \( F(x_k) + F'(x_k)d_0 \in C \). Consequently, by Remark 3.1,
\[ D_\Delta(x_k) = \{ d \in \mathbb{R}^n : \|d\| \leq \Delta, F(x_k) + F'(x_k)d \in C \} \]
and
\[ d(0, D_\Delta(x_k)) = d(0, D(x_k)). \]
Since \( d_k = x_{k+1} - x_k \in D_\Delta(x_k) \) by Algorithm A \((\eta, \Delta, x_0)\), it follows that (4.7) holds for \( n = k \). Furthermore, one has that
\[
\|x_{k+1} - x_k\| \leq \eta d(0, D_\Delta(x_k)) = \eta d(0, D(x_k)).
\]
This with (4.17) yields that (4.6) holds for \( n = k \), and hence implication (4.12) is proved.

Clearly, if (4.5) holds for each \( n = 1, 2, \ldots \), then \( \{x_n\} \) is a Cauchy sequence by the monotonicity of \( \{t_n\} \) and hence converges to some \( x^* \). Thus (4.8) is clear. Therefore, to prove the theorem, we need to prove only that (4.5), (4.6), and (4.7) hold for each \( n = 1, 2, \ldots \). We will proceed by mathematical induction. First, by (4.1), (4.3), and (4.11), \( D(x_0) \neq \emptyset \) and
\[
\eta d(0, D(x_0)) \leq \eta \beta x_0(\|x_0 - x_0\|) d(F(x_0), C) = \eta \beta x_0(0) d(F(x_0), C) = \xi \leq \Delta.
\]
Then using the same arguments just used above, we have that (4.7) holds for \( n = 0 \) and
\[
\|x_1 - x_0\| = \|d_0\| \leq \eta d(0, D_\Delta(x_0)) \leq \eta \beta x_0(0) d(F(x_0), C) = \xi = t_{\alpha,1} - t_{\alpha,0};
\]
that is, (4.5) holds for \( n = 1 \). Thus, by (4.12), (4.6) and (4.7) hold for \( n = 1 \). Furthermore, assume that (4.5), (4.6), and (4.7) hold for each \( 1 \leq n \leq k \). Then
\[
\|x_{k+1} - x_k\| \leq (t_{\alpha,k+1} - t_{\alpha,k}) \left( \frac{\|x_k - x_{k-1}\|}{t_{\alpha,k} - t_{\alpha,k-1}} \right)^2 \leq t_{\alpha,k+1} - t_{\alpha,k}.
\]
This shows that (4.5) holds for \( n = k + 1 \), and hence (4.5) holds for all \( n \) with \( 1 \leq n \leq k + 1 \). Thus, (4.12) implies that (4.6) and (4.7) hold for \( n = k + 1 \). Therefore, (4.5), (4.6), and (4.7) hold for each \( n = 1, 2, \ldots \). The proof is complete.  

Remark 4.1. (a) In Theorem 4.1 if one assumes in addition that either (i) \( \xi < b_\alpha \) or (ii) \( \alpha > \alpha_0 := \alpha_0(\mathbf{r}) \), then the convergence of the sequence \( \{x_n\} \) is of quadratic rate. For the case of (i), this remark follows immediately from Lemma 2.1(iii) thanks to (4.5) and (4.8). If (ii) is assumed, then, by Lemma 2.2, \( \xi \leq b_\alpha < b_{\alpha_0} \) and \( r_\alpha \leq r_0^* \leq r \). Hence (4.3) holds with \( \alpha_0 \) in place of \( \alpha \). Since \( \xi < b_{\alpha_0} \), we are now in the case (i) if \( \alpha \) is replaced by \( \alpha_0 \), and hence our remark here is established.

(b) Refinements for results presented in the remainder of this paper can also be established in a similar manner as in (a) above.

Remark 4.2. Suppose that there exists a pair \((\bar{\alpha}, \mathbf{\bar{r}})\) such that
\[
\begin{align*}
\bar{\alpha} &= \alpha_0(\mathbf{r}), \\
\bar{r}_\alpha^* &= \mathbf{r}.
\end{align*}
\]
Note that the function \( \alpha \mapsto b_\alpha \) is decreasing by Lemma 2.2. Then, if (4.3) holds for some \((\alpha, r)\) with \( \alpha \geq \bar{\alpha} \) and \( r \geq \mathbf{\bar{r}} \), (4.3) does for \((\alpha, r) = (\bar{\alpha}, \mathbf{\bar{r}})\) (and hence Theorem 4.1 is applicable).

Recall from Proposition 3.3 that the assumption for the existence of \( r_\alpha, \beta \) in the following corollary is automatically satisfied when \( x_0 \in \mathbb{R}^n \) is a regular point of the inclusion (3.1). This remark also applies to Theorems 5.1 and 5.6 and Corollary 5.2.

Corollary 4.2. Let \( x_0 \in \mathbb{R}^n \) be a regular point of the inclusion (3.1) with \( r > 0 \) and \( \beta > 0 \) such that
\[
\begin{align*}
D(x) \neq \emptyset \quad \text{and} \quad d(0, D(x)) \leq \beta d(F(x), C) \quad \text{for all} \ x \in B(x_0, r).
\end{align*}
\]
Let $\eta \in [1, \infty)$, $\Delta \in (0, \infty)$, $\xi = \eta \beta d(F(x_0), C)$,

(4.24) \[ \alpha = \frac{\eta \beta}{1 + \eta \beta \int_0^\xi L(u) \, du}, \]

and let $b_\alpha, r_\alpha$ be defined by (2.1). Let $r^*_\alpha$ denote the smaller zero of the function $\phi_\alpha$ defined by (2.2). Suppose that $F'$ satisfies the $L$-average Lipschitz condition on $B(x_0, r^*_\alpha)$ and that

(4.25) \[ \xi \leq \min\{b_\alpha, \Delta\} \quad \text{and} \quad r^*_\alpha \leq r \]

(for example, (4.25) is satisfied if $\xi \leq \min\{b_\alpha, b_\alpha r, \Delta\}$). Then the conclusions of Theorem 4.1 hold.

Proof. Note that $\xi < r^*_\alpha \leq r$ by Lemma 2.1 and (4.25). By (3.6) and (3.7), it is clear that $r_{x_0} \geq r$ and $\beta_{x_0}(t) \leq \beta$ on $[0, r)$. Let $r := r$, and let $\alpha_0(r)$ be defined by (4.2) as in Theorem 4.1. Then, by (4.24), we have that

(4.26) \[ \alpha \geq \frac{\eta \beta_{x_0}(t)}{1 + \eta \beta_{x_0}(t) \int_0^t L(u) \, du} \quad \text{for each} \quad t \in [\xi, r). \]

Hence $\alpha \geq \alpha_0(r)$ by (4.2). Note that (4.26) (resp., (4.25)) is identical to (4.4) (resp., (4.3)); Theorem 4.1 is applicable, and the proof is complete. \qed

**Corollary 4.3.** Let $\eta \in [1, +\infty)$, $\Delta \in (0, +\infty]$, and let $C$ be a cone. Let $x_0 \in \mathbb{R}^v$ be such that $T_{x_0}$ carries $\mathbb{R}^v$ onto $\mathbb{R}^m$. Let

(4.27) \[ \xi = \eta \|T_{x_0}^{-1}\| d(F(x_0), C), \]

(4.28) \[ \alpha = \frac{\eta \|T_{x_0}^{-1}\|}{1 + (\eta - 1)\|T_{x_0}^{-1}\| \int_0^\xi L(u) \, du}, \]

and let $b_\alpha, r_\alpha$ be defined by (2.1). Let $r^*_\alpha$ denote the smaller zero of the function $\phi_\alpha$ defined by (2.2). Suppose that $F'$ satisfies the $L$-average Lipschitz condition on $B(x_0, r^*_\alpha)$ and that

(4.29) \[ \xi \leq \min\{b_\alpha, \Delta\}. \]

Then the conclusions of Theorem 4.1 hold.

Proof. Let $\beta_0 = \|T_{x_0}^{-1}\|$, and let $r_{\beta_0}$ be defined by (3.13). Then, by Proposition 3.7(ii), we know that $x_0$ is a quasi-regular point with the quasi-regular radius

(4.30) \[ r_{x_0} \geq \min\{r^*_\alpha, r_{\beta_0}\} \]

and the quasi-regular bound function

(4.31) \[ \beta_{x_0}(t) \leq \frac{\beta_0}{1 - \beta_0 \int_0^t L(u) \, du} \quad \text{for each} \quad t \in [0, \min\{r^*_\alpha, r_{\beta_0}\}). \]
Let $r := \min\{r^*_\alpha, r_{\beta_0}\}$, and let $\alpha_0(r)$ be defined by (4.2). We claim that
\begin{equation}
\alpha \geq \alpha_0(r) \tag{4.32}
\end{equation}
and
\begin{equation}
r_{\beta_0} \geq r^*_\alpha \tag{4.33}
\end{equation}
Granting this, the minimum on the right-hand side of (4.30) is simply $r^*_\alpha$, and so $r = r^*_\alpha \leq r_{x_0}$. Moreover, we note that $\beta_{x_0}(0) \leq \beta_0$ by (4.31), and so the $\xi$ defined by (4.1) is majorized by that defined by (4.27); thus (4.29) entails that (4.3) holds and Theorem 4.1 is applicable. Therefore we need only to prove our claim. Note by (4.31) that, for each $\xi \leq \eta < \min\{r^*_\alpha, r_{\beta_0}\} = r$, we have
\begin{equation}
\eta \int_0^t L(u) \, du + \frac{1}{\beta_{x_0}(t)} \leq \frac{1}{\beta_0} + (\eta - 1) \int_0^t L(u) \, du \geq \frac{1}{\beta_0} + (\eta - 1) \int_0^\xi L(u) \, du; \tag{4.34}
\end{equation}
that is,
\begin{equation}
\frac{\beta_{x_0}(t)}{1 + \eta\beta_{x_0}(t) \int_0^t L(u) \, du} \leq \frac{\beta_0}{1 + (\eta - 1)\beta_0 \int_0^t L(u) \, du}. \tag{4.35}
\end{equation}
Thus (4.32) follows by definitions of $\alpha_0(r)$ and of $\alpha$, respectively given by (4.2) and (4.28). To verify (4.33), consider the two cases (i) $\alpha \geq \beta_0$ and (ii) $\alpha < \beta_0$. In (i), since by Lemma 2.2, $r_\alpha$ is decreasing with respect to $\alpha$, we have that $r^*_\alpha \leq r_\alpha \leq r_{\beta_0}$. In (ii), since $r^*_\alpha$ is increasing with respect to $\alpha$ by Lemma 2.2, we have that $r^*_\alpha \leq r^*_\beta_0 \leq r_{\beta_0}$. Therefore, (4.33) holds in all cases, and the proof is complete.

Remark 4.3. (a) If the strict inequalities in (4.25) (resp., (4.29)) of Corollary 4.2 (resp., Corollary 4.3) hold, then the starting point $x_0$ of the sequence $\{x_n\}$ can be replaced by a nearby point; that is, there exists a neighborhood $U(x_0)$ of $x_0$ such that the sequence $\{x_n\}$ generated by Algorithm A ($\eta, \Delta, \bar{x}$) with initial point $\bar{x}$ from $U(x_0)$ converges to some solution of the inclusion problem (3.1) at a quadratic rate.
(b) Refinements for results presented in the remainder of this paper can also be established in a similar manner as in (a) above.

5. Special cases and applications. This section is devoted to some applications. First we specialize results of the preceding section to two important cases of the function $L$: $L =$ constant and $L = \frac{2\gamma}{1 - \gamma u^2}$. Second, mimicking Smale’s $\gamma$-theory about the approximation zeros for Newton’s method in solving nonlinear equations, we do the same for the Gauss–Newton method in solving composite convex optimization.

5.1. Kantorovich type. Throughout this subsection, we assume that the function $L$ is a constant function. Then, by (2.1) and (2.2), we have that, for all $\alpha > 0$,
\begin{equation}
r_\alpha = \frac{1}{\alpha L}, \quad b_\alpha = \frac{1}{2\alpha L} \tag{5.1}
\end{equation}
and
\begin{equation}
\phi_\alpha(t) = \xi - t + \frac{\alpha L}{2} t^2. \tag{5.2}
\end{equation}
Moreover, if $\xi \leq \frac{1}{2\alpha L}$, then the zeros of $\phi_\alpha$ are given by
\begin{equation}
\frac{r^*_\alpha}{r^{**}_\alpha} = \frac{1 + \sqrt{1 - 2\alpha L\xi}}{\alpha L}. \tag{5.2}
\end{equation}
It is also known (see, for example, [8, 17, 29]) that \( \{t_{\alpha,n}\} \) has the closed form
\[
t_{\alpha,n} = \frac{1 - q_\alpha^{n-1}}{1 - q_\alpha^{2n}} r_\alpha^* \quad \text{for each } n = 0, 1, \ldots,
\]
where
\[
q_\alpha := \frac{r_\alpha^*}{r_\alpha^{2n}} = \frac{1 - \sqrt{1 - 2\alpha L^2 \xi}}{1 + \sqrt{1 - 2\alpha L^2 \xi}}.
\]

For the present case (\( L \) is a positive constant), a commonly used version of Lipschitz continuity on \( B(x_0, r) \) is of course the following: a function \( G \) is Lipschitz continuous with modulus \( L \) (Lipschitz constant) if
\[
\|G(x_1) - G(x_2)\| \leq L \|x_1 - x_2\| \quad \text{for all } x_1, x_2 \in B(x_0, r).
\]
Clearly, this is a stronger requirement than the corresponding ones given in Definition 2.5. Although the weaker requirement of Definition 2.5(b) is sufficient for results in this subsection, we prefer to use the Lipschitz continuity in this regard to be in line with the common practice.

**Theorem 5.1.** Let \( x_0 \in \mathbb{R}^\nu \) be a regular point of the inclusion (3.1) with \( r > 0 \) and \( \beta > 0 \) such that (4.23) holds. Let \( L \in (0, +\infty) \), \( \eta \in [1, +\infty) \), \( \Delta \in (0, +\infty] \), \( \xi = \eta \beta d(F(x_0), C) \), \( R^* = 1 + L \eta \beta \xi - \sqrt{1 - (L \eta \beta \xi)^2} \), and \( Q = \frac{1 - \sqrt{1 - (L \eta \beta \xi)^2}}{L \eta \beta \xi} \).
\[
R^* = \frac{1 + L \eta \beta \xi - \sqrt{1 - (L \eta \beta \xi)^2}}{L \eta \beta} \quad \text{and} \quad Q = \frac{1 - \sqrt{1 - (L \eta \beta \xi)^2}}{L \eta \beta \xi}.
\]
Assume that \( F' \) is Lipschitz continuous on \( B(x_0, R^*) \) with modulus \( L \), and that
\[
\xi \leq \min \left\{ \frac{1}{L \beta \eta}, \Delta \right\} \quad \text{and} \quad r \geq R^*
\]
(for example, (5.6) is satisfied if
\[
\xi \leq \min \left\{ \frac{1}{L \beta \eta}, \frac{1}{2} r, \Delta \right\}
\]
holds). Let \( \{x_n\} \) denote the sequence generated by Algorithm A (\( \eta, \Delta, x_0 \)). Then \( \{x_n\} \) converges to some \( x^* \) with \( F(x^*) \in C \) and
\[
\|x_n - x^*\| \leq \frac{Q^{2^n - 1} R^*}{\sum_{i=0}^{2^n-1} Q^i} \quad \text{for each } n = 0, 1, \ldots.
\]

**Proof.** Let \( \alpha \) be given as in (4.24), namely, \( \alpha = \frac{\eta \xi}{1 + L \eta \beta \xi} \). Moreover, by (5.1)–(5.5), one has that
\[
r_\alpha^* = R^*, \quad q_\alpha = Q, \quad r_\alpha = \frac{1 + L \eta \beta \xi}{L \eta \beta}, \quad b_\alpha = \frac{1 + L \eta \beta \xi}{2L \eta \beta}
\]
and
\[
t_{\alpha,n} = \frac{1 - Q^{2^n - 1}}{1 - Q^{2^n}} R^*.
\]
Hence condition (4.3) (resp., (4.4)) is equivalent to the three inequalities
\[
\eta \leq \frac{1 + L\eta\bar{\beta}\xi}{2L\eta^3}, \quad \xi \leq \Delta, \quad \text{and} \quad r^*_\alpha \leq r \quad \text{(resp.,} \quad \xi \leq \frac{b\alpha}{r\alpha}r)\quad \frac{1 + L\eta\bar{\beta}\xi}{2L\eta^3}, \quad \xi \leq \Delta, \quad \text{and} \quad r^*_\alpha \leq r \quad \text{(resp.,} \quad \xi \leq \frac{b\alpha}{r\alpha}r),
\]
and is hence, by (5.9), also equivalent to condition (5.6) (resp., (5.7)). Thus we apply Corollary 4.2 to conclude that the sequence \( \{x_n\} \) converges to some \( x^* \) with \( F(x^*) \in C \) and, for each \( n = 1, 2, \ldots, \)
\[
||x_n - x^*|| \leq r^*_\alpha - t^*_{\alpha,n}.
\]
Noting, by (5.9) and (5.10), that
\[
\bar{r}^* = \left(1 - \frac{1 - Q^{2n-1}}{1 - Q^{2n}}\right) R^* = \frac{Q^{2n-1}}{\sum_{i=0}^{2n-1} Q^i} R^*,
\]
it follows that (5.8) holds, and the proof is complete. \( \square \)

The following corollary (which requires no proof by virtue of Theorem 5.1 and Remark 4.3(a)) is a slight extension of [13, Theorem 1] (which, in turn, extends a result of Burke and Ferris [4, Theorem 4.1]), and our conditions such as (5.11) are more direct than the corresponding ones in [13]. In fact, the conditions (a)–(c) of [13, Theorem 1] clearly imply the condition (5.11) below. Moreover, by (a) and (b) of [13, Theorem 1], \( \delta > 4\eta\bar{\beta}d(F(\bar{x}), C) = 4\xi. \) Since, for each \( \xi \leq \frac{1}{L\eta\beta}, \)
\[
1 + \frac{L\eta\bar{\beta}\xi - \sqrt{1 - (L\eta\bar{\beta}\xi)^2}}{L\eta^3} \leq 2,
\]
one has that
\[
1 + \frac{L\eta\bar{\beta}\xi - \sqrt{1 - (L\eta\bar{\beta}\xi)^2}}{L\eta^3} = \frac{1 + L\eta\bar{\beta}\xi - \sqrt{1 - (L\eta\bar{\beta}\xi)^2}}{L\eta\bar{\beta}} \bar{\xi} \leq 2\bar{\xi} < \bar{\delta}.
\]
Hence, \( \bar{r}^* := \bar{\delta} \) satisfies the requirements of Corollary 5.2 below.

Corollary 5.2. Let \( \bar{x} \in \mathbb{R}^v \) be a regular point of the inclusion (3.1) with positive constants \( \bar{r} \) and \( \bar{\beta} \) satisfying (4.23) in place of \( r \) and \( \beta \), respectively. Let \( L \in (0, +\infty), \eta \in [1, +\infty), \Delta \in (0, +\infty], \bar{\xi} = \eta\bar{\beta}d(F(\bar{x}), C), \) and let \( \bar{r}^* > \frac{1 + L\eta\bar{\beta}\xi - \sqrt{1 - (L\eta\bar{\beta}\xi)^2}}{L\eta\bar{\beta}} \).
Assume that \( F' \) is Lipschitz continuous on \( B(\bar{x}, \bar{r}^*) \) with modulus \( L \), and that
\[
(5.11) \quad \bar{\xi} < \min \left\{ \frac{1}{L\eta\beta}, \frac{1}{2\bar{r}}, \Delta \right\}.
\]
Then, there exists a neighborhood \( U(\bar{x}) \) of \( \bar{x} \) such that the sequence \( \{x_n\} \) generated by Algorithm A (\( \eta, \Delta, x_0 \)) with \( x_0 \in U(\bar{x}) \) converges at a quadratic rate to some \( x^* \) with \( F(x^*) \in C, \) and the estimate (5.8) holds.

Theorem 5.3. Let \( \eta \in [1, +\infty), \Delta \in (0, +\infty], \) and let \( C \) be a cone. Let \( x_0 \in \mathbb{R}^v \) be such that \( T_{x_0} \) carries \( \mathbb{R}^v \) onto \( \mathbb{R}^m. \) Let \( L \in (0, +\infty) \) and \( \xi = \eta\|T_{x_0}^{-1}\|d(F(x_0), C). \) Instead of (5.5), we write
\[
(5.12) \quad R^* = \frac{1 + (\eta - 1)L\|T_{x_0}^{-1}\|\xi - \sqrt{1 - 2L\|T_{x_0}^{-1}\|\xi - (\eta^2 - 1)(L\|T_{x_0}^{-1}\|\xi)^2}}{L\|T_{x_0}^{-1}\|\eta}
\]
and
\begin{equation}
Q = \frac{1 - L\|T^{-1}_{x_0}\|\xi - \sqrt{1 - 2L\|T^{-1}_{x_0}\|\xi - (\eta^2 - 1)(L\|T^{-1}_{x_0}\|\xi)^2}}{L\|T^{-1}_{x_0}\|\eta\xi}.
\end{equation}

Suppose that $F'$ is Lipschitz continuous on $B(x_0, R^*)$ with modulus $L$, and that
\begin{equation}
\xi \leq \min \left\{ \frac{1}{L\|T^{-1}_{x_0}\|(\eta + 1)}, \Delta \right\}.
\end{equation}

Then, the same conclusions hold as in Theorem 5.1.

\textbf{Proof.} Let $\alpha$ be defined as in (4.28); that is, $\alpha = \frac{\eta\|T^{-1}_{x_0}\|}{1 + (\eta - 1)L\|T^{-1}_{x_0}\|\xi}$. Then, by (5.1), the following equivalences hold:
\begin{align*}
\xi &\leq b_\alpha \iff 2L\xi\|T^{-1}_{x_0}\| \leq 1 + (\eta - 1)L\|T^{-1}_{x_0}\|\xi \iff \xi L\|T^{-1}_{x_0}\| (1 + \eta) \leq 1;
\end{align*}
that is, (4.29) and (5.14) are equivalent. Moreover, it is easy to verify that $R^*$ and $Q$ defined in (5.12) and (5.13), respectively, are equal to $r^*_\alpha$ and $q_\alpha$ defined in (5.2) and (5.4). Therefore, one can complete the proof in the same way as for Theorem 5.1 but using Corollary 4.3 in place of Corollary 4.2. \hfill \Box

5.2. Smale’s type. Let $\gamma > 0$. For the remainder of this section we assume that $L$ is the function defined by
\begin{equation}
L(u) = \frac{2\gamma}{(1 - \gamma u)^3} \quad \text{for each } u \text{ with } 0 \leq u < \frac{1}{\gamma}.
\end{equation}
Then, by (2.1), (2.2), and elementary calculation (cf. [28]), one has that for all $\alpha > 0$,
\begin{equation}
r_\alpha = \left(1 - \sqrt{\frac{\alpha}{1 + \alpha}}\right)^{\frac{1}{\gamma}}, \quad b_\alpha = \left(1 + 2\alpha - 2\sqrt{\alpha(1 + \alpha)}\right)^{\frac{1}{\gamma}}
\end{equation}
and
\begin{equation}
\phi_\alpha(t) = \xi - t + \frac{\alpha\gamma t^2}{1 - \gamma t} \quad \text{for each } t \text{ with } 0 \leq t < \frac{1}{\gamma}.
\end{equation}

Thus, from [28], we have the following lemma.

\textbf{Lemma 5.4.} Let $\alpha > 0$. Assume that $\xi \leq b_\alpha$, namely,
\begin{equation}
\gamma\xi \leq 1 + 2\alpha - 2\sqrt{\alpha(1 + \alpha)}.
\end{equation}

Then the following assertions hold:
(i) $\phi_\alpha$ has two zeros given by
\begin{equation}
\begin{aligned}
r^*_\alpha \\
r^{**}_\alpha
\end{aligned}
\end{equation}
\begin{equation}
= \frac{1 + \gamma\xi \mp \sqrt{(1 + \gamma\xi)^2 - 4(1 + \alpha)\gamma\xi}}{2(1 + \alpha)\gamma}.
\end{equation}
(ii) The sequence $\{t_{\alpha,n}\}$ generated by Newton’s method for $\phi_\alpha$ with initial point $t_{\alpha,0} = 0$ has the closed form
\begin{equation}
t_{\alpha,n} = \frac{1 - q_\alpha^{n-1}}{1 - q_\alpha^{n-1}p_\alpha} r^*_\alpha \quad \text{for each } n = 0, 1, \ldots,
\end{equation}
where

\[
q_\alpha := \frac{1 - \gamma \xi - \sqrt{(1 + \gamma \xi)^2 - 4(1 + \alpha)\gamma \xi}}{1 - \gamma \xi + \sqrt{(1 + \gamma \xi)^2 - 4(1 + \alpha)\gamma \xi}} \quad \text{and} \quad
\]

\[
p_\alpha := \frac{1 + \gamma \xi - \sqrt{(1 + \gamma \xi)^2 - 4(1 + \alpha)\gamma \xi}}{1 + \gamma \xi + \sqrt{(1 + \gamma \xi)^2 - 4(1 + \alpha)\gamma \xi}}
\]

(5.20)

(iii)

\[
\frac{t_{\alpha,n+1} - t_{\alpha,n}}{t_{\alpha,n} - t_{\alpha,n-1}} = \frac{1 - q_\alpha^n}{1 - q_\alpha^{n-1}} \cdot \frac{1 - q_\alpha^{2n-1}}{1 - q_\alpha^{2n+1}} p_\alpha q_\alpha^{2n-1} \leq q_\alpha 2^{n-1}.
\]

(5.21)

For the following lemma, we define, for \( \xi > 0 \),

\[
I(\xi) = \{ \alpha > 0 : \xi \leq b_\alpha \} = \{ \alpha > 0 : \gamma \xi \leq 1 + 2\alpha - 2\sqrt{\alpha(1 + \alpha)} \}.
\]

(5.22)

Sometimes in order to emphasize the dependence, we write \( q(\alpha, \xi) \) for \( q_\alpha \) defined by (5.20).

**Lemma 5.5.** The following assertions hold:

(i) For each \( \alpha > 0 \), the function \( q(\alpha, \cdot) \) is strictly increasing on \((0, b_\alpha]\).

(ii) For each \( \xi > 0 \), the function \( q(\cdot, \xi) \) is strictly increasing on \( I(\xi) \).

**Proof.** We prove only the assertion (i), as (ii) can be proved similarly. Let \( \alpha > 0 \).

Define

\[
g_1(t) = (1 + t)^2 - 4(1 + \alpha)t \quad \text{for each } t
\]

and

\[
g_2(t) = 1 - t + \sqrt{g_1(t)} \quad \text{for each } t \in (0, 1 + 2\alpha - 2\sqrt{\alpha(1 + \alpha)}].
\]

Then,

\[
g_1'(t) = 2(1 + t) - 4(1 + \alpha) \quad \text{for each } t
\]

and

\[
g_2'(t) = -1 + \frac{g_1'(t)}{2\sqrt{g_1(t)}} = \frac{g_1'(t) - 2\sqrt{g_1(t)}}{2\sqrt{g_1(t)}} \quad \text{for each } t \in (0, 1 + 2\alpha - 2\sqrt{\alpha(1 + \alpha)}].
\]

Define

\[
g(t) = 1 - \frac{2\sqrt{g_1(t)}}{g_2(t)} \quad \text{for each } t \in (0, 1 + 2\alpha - 2\sqrt{\alpha(1 + \alpha)}].
\]

Then, for each \( t \in (0, 1 + 2\alpha - 2\sqrt{\alpha(1 + \alpha)}], \)

\[
g'(t) = -\frac{g_1'(t)g_2(t) + 2g_1(t) - \sqrt{g_1(t)}g_1'(t)}{g_2^2(t)\sqrt{g_1(t)}} = -\frac{(1-t)g_1'(t) + 2g_1(t)}{g_2^2(t)\sqrt{g_1(t)}}.
\]

Since (as can be verified easily)

\[
(1-t)g_1'(t) + 2g_1(t) = -4\alpha(1 + t) < 0,
\]
it follows that \( g' > 0 \) on \((0, 1 + 2\alpha - 2\sqrt{\alpha(1 + \alpha)})\), and hence \( g \) is increasing on \((0, 1 + 2\alpha - 2\sqrt{\alpha(1 + \alpha)})\). Noting that 
\[
q(\alpha, \xi) = g(\gamma \xi) \quad \text{for each } \xi \in (0, b_{\alpha}],
\]
the desired conclusion holds. The proof is complete.

**Theorem 5.6.** Let \( x_0 \in \mathbb{R}^n \) be a regular point of the inclusion (3.1) with \( r > 0 \) and \( \beta > 0 \) such that (4.23) holds. Let \( \eta \in [1, +\infty), \Delta \in (0, +\infty], \xi = \eta \beta d(F(x_0), C), \) and \( \alpha = \frac{\eta \beta (1 - \gamma \xi)^2}{\eta \beta + (1 - \eta \beta)(1 - \gamma \xi)^2}. \) Set 
\[
(5.23) \quad r_{\alpha}^* = \frac{1 + \gamma \xi - \sqrt{(1 + \gamma \xi)^2 - 4(1 + \alpha)\gamma \xi}}{2(1 + \alpha)\gamma} \quad \text{and} \quad q_{\alpha} = \frac{1 - \gamma \xi - \sqrt{(1 + \gamma \xi)^2 - 4(1 + \alpha)\gamma \xi}}{1 - \gamma \xi + \sqrt{(1 + \gamma \xi)^2 - 4(1 + \alpha)\gamma \xi}}.
\]
Assume that \( F' \) satisfies the \( L \)-average Lipschitz condition on \( B(x_0, r_{\alpha}^*) \) and that 
\[
(5.24) \quad \xi \leq \min \left\{ \frac{1 + 2\eta \beta - 2\sqrt{\eta \beta(1 + \eta \beta)}}{\gamma}, \frac{1 + 2\eta \beta - 2\sqrt{\eta \beta(1 + \eta \beta)}}{1 + \eta \beta - \sqrt{\eta \beta(1 + \eta \beta)}} r, \Delta \right\}.
\]
Let \( \{x_n\} \) denote the sequence generated by Algorithm A \( (\eta, \Delta, x_0) \). Then \( \{x_n\} \) converges at a quadratic rate to some \( x^* \) with \( F(x^*) \in C, \) and the following assertions hold: 
\[
(5.25) \quad \|x_n - x^*\| \leq q_{\alpha} 2^{n-1} r_{\alpha}^* \quad \text{for all } n = 0, 1, \ldots
\]
and 
\[
(5.26) \quad \|x_{n+1} - x_n\| \leq q_{\alpha} 2^{n-1} \|x_n - x_{n-1}\| \quad \text{for all } n = 1, 2, \ldots.
\]

**Proof.** By (5.15), 
\[
\int_0^\xi L(u) \, du = (1 - \gamma \xi)^2 - 1; \quad \text{hence } \alpha \text{ given in the statement of the theorem is consistent with (4.24). Set } \alpha' = \eta \beta. \text{ Then, by (5.16),}
\]
\[
(5.27) \quad b_{\alpha'} = \frac{1}{\gamma} \left( 1 + 2\eta \beta - 2\sqrt{\eta \beta(1 + \eta \beta)} \right)
\]
and 
\[
(5.28) \quad \frac{b_{\alpha'}}{r_{\alpha'}} = \frac{1 + 2\eta \beta - 2\sqrt{\eta \beta(1 + \eta \beta)}}{1 + \eta \beta - \sqrt{\eta \beta(1 + \eta \beta)}} (1 + \eta \beta).
\]
Thus (5.24) reads 
\[
(5.29) \quad \xi \leq \min \left\{ b_{\alpha'}, \frac{b_{\alpha'}}{r_{\alpha'}}, r, \Delta \right\}.
\]
Since \( \gamma \xi < 1 \) by (5.24), it is clear from the definition of \( \alpha \) that \( \alpha < \alpha' \) if \( \xi > 0 \) and \( \alpha = \alpha' \) if \( \xi = 0 \). Since the function \( u \mapsto b_u \) strictly decreasing by Lemma 2.2, it follows that if \( \xi > 0, \)
\[
(5.29) \quad b_{\alpha'} < b_{\alpha}.
\]
We claim that
\[
\xi < b_\alpha, \quad \xi \leq \Delta, \quad \text{and} \quad r_\alpha^* < r.
\]
In fact, this claim is trivially true if \( \xi = 0 \), and so we can assume that \( \xi > 0 \).
Then the first two inequalities follow from (5.28) and (5.29), while the last inequality
follows from the fact that \( r_\alpha^* < r_\alpha^{\prime} \leq \frac{r_\alpha^2}{b_\alpha^2} \xi \leq r \) thanks to (5.28), Lemma 2.1(i),
and Lemma 2.2(iii). Therefore, (5.30) is true. Moreover, by (5.30) and (5.16), \( \gamma \xi < 1 + 2\alpha - 2\sqrt{\alpha(1 + \alpha)} \),
the smaller root of the function \( t \to (1 + t)^2 - 4(1 + \alpha)t \).
Therefore, \( (1 + \gamma \xi)^2 - 4(1 + \alpha)\gamma \xi > 0 \), and so \( q_\alpha < 1 \) by (5.33).
Now, by Corollary 4.2, the sequence \( \{x_n\} \) converges to some \( x^* \) with \( F(x^*) \in C \),
and the following estimates hold for each \( n \):
\[
\|x_n - x^*\| \leq r_\alpha^* - t_{\alpha,n},
\]
\[
\|x_{n+1} - x_n\| \leq (t_{\alpha,n+1} - t_{\alpha,n}) \left( \frac{\|x_n - x_{n-1}\|}{t_{\alpha,n} - t_{\alpha,n-1}} \right)^2
\]
\[
\leq \left( \frac{t_{\alpha,n+1} - t_{\alpha,n}}{t_{\alpha,n} - t_{\alpha,n-1}} \right) \|x_n - x_{n-1}\|.
\]
Hence (5.25) and (5.26) are true because, by (5.19) and (5.21), one has
\[
r_\alpha^* - t_{\alpha,n} = q_\alpha^{2^n-1}(1 - p_\alpha) \gamma \xi \leq q_\alpha^{2^n-1} r_\alpha^*
\]
and
\[
t_{\alpha,n+1} - t_{\alpha,n} \leq q_\alpha^{2^n-1}.
\]
Thus the convergence of \( \{x_n\} \) is quadratic, and the proof is complete.

The following result can be proved similarly, but applying Corollary 4.3 in place of Corollary 4.2,
and using \( \alpha' := \eta\|T_{x_0}^{-1}\| \) (thus \( b_\alpha' = \frac{1 + 2\alpha\|T_{x_0}^{-1}\| - 2\sqrt{\eta\|T_{x_0}^{-1}\|\|T_{\gamma}^{-1}\|}}{\gamma} \)).

**Theorem 5.7.** Let \( \eta \in [1, +\infty) \), \( \Delta \in (0, +\infty) \), and let \( C \) be a cone. Let \( x_0 \in \mathbb{R}^v \)
such that \( T_{x_0} \) carries \( \mathbb{R}^v \) onto \( \mathbb{R}^m \). Let \( \xi = \eta\|T_{x_0}^{-1}\|d(F(x_0), C) \) and
\[
\alpha = \frac{\eta\|T_{x_0}^{-1}\|((1 - \gamma \xi)^2)}{(\eta - 1)\|T_{x_0}^{-1}\| + (1 - (\eta - 1)\|T_{x_0}^{-1}\|)(1 - \gamma \xi)^2}.
\]
Set, as in (5.23),
\[
r_\alpha^* = \frac{1 + \gamma \xi - \sqrt{(1 + \gamma \xi)^2 - 4(1 + \alpha)\gamma \xi}}{2(1 + \alpha)\gamma} \quad \text{and} \quad q_\alpha = \frac{1 - \gamma \xi - \sqrt{(1 + \gamma \xi)^2 - 4(1 + \alpha)\gamma \xi}}{1 - \gamma \xi + \sqrt{(1 + \gamma \xi)^2 - 4(1 + \alpha)\gamma \xi}}.
\]
Suppose that \( F' \) satisfies the \( L \)-average Lipschitz condition on \( B(x_0, r_\alpha^*) \) and that
\[
\xi \leq \min \left\{ \frac{1 + 2\eta\|T_{x_0}^{-1}\| - 2\sqrt{\eta\|T_{x_0}^{-1}\|\|T_{\gamma}^{-1}\|}}{\gamma}, \Delta \right\}.
\]
Then the conclusions hold as in Theorem 5.6.
5.3. Extension of Smale’s approximate zeros. The following notion of approximate zeros was introduced in [26] for Newton’s method. Let \( f \) be an operator from a domain \( D \) in a Banach space \( X \) to another one \( Y \). Recall that Newton’s iteration for \( f \) is defined as follows:

\[
  x_{n+1} = x_n - f'(x_n)^{-1} f(x_n), \quad n = 0, 1, \ldots .
\]

The sequence \( \{x_n\} \) is said to satisfy Smale’s condition if

\[
  \|x_{n+1} - x_n\| \leq \left( \frac{1}{2} \right)^{n-1} \|x_n - x_{n-1}\| \quad \text{for each} \quad n = 1, 2, \ldots .
\]

(5.38)

Note that (5.38) implies that \( \{x_n\} \) is a Cauchy sequence and hence converges (with limit denoted by \( x^* \)). By (5.37) it follows that \( x^* \) is a zero of \( f \).

Definition 5.8. Suppose that \( x_0 \in D \) is such that Newton iteration (5.37) is well defined for \( f \) and \( \{x_n\} \) satisfies Smale’s condition. Then \( x_0 \) is said to be an approximate zero of \( f \).

Recall that if \( x_0 \) is an approximate zero of \( f \), then Newton iteration (5.37) converges to a zero \( x^* \) of \( f \). We now extend the notion of approximate zeros to the Gauss–Newton method for convex composite optimization problems.

Definition 5.9. Suppose that \( x_0 \in D \) is such that the sequence \( \{x_n\} \) generated by Algorithm A (\( \eta, \Delta, x_0 \)) converges to a limit \( x^* \) solving (1.1) and satisfies Smale’s condition. Then \( x_0 \) is said to be an \( (\eta, \Delta) \)-approximate solution of (1.1).

Recall that \( L \) is defined by (5.15).

Theorem 5.10. Let \( x_0 \in \mathbb{R}^v \) be a regular point of the inclusion (3.1) with \( r > 0 \) and \( \beta > 0 \) such that (4.23) holds. Let \( \eta \in [1, +\infty), \Delta \in (0, +\infty), \xi = \eta\beta d(F(x_0), C), \) and

\[
  \hat{R} = \left(1 - \sqrt{\frac{\eta\beta}{1 + \eta\beta}} \right) \frac{1}{\gamma}.
\]

Suppose that \( F' \) satisfies the \( L \)-average Lipschitz condition on \( B(x_0, \hat{R}) \) and that

\[
  \xi \leq \min \left\{ \frac{4 + 9\eta\beta - 3\sqrt{\eta\beta(9\eta\beta + 8)}}{4\gamma}, \frac{1 + 2\eta\beta - 2\sqrt{\eta\beta(1 + \eta\beta)}}{1 + \eta\beta - \sqrt{\eta\beta(1 + \eta\beta)}}, \frac{r, \Delta}{r, \Delta} \right\}.
\]

(5.39)

Then, \( x_0 \) is an \( (\eta, \Delta) \)-approximate solution of (1.1).

Proof. Let \( \alpha \) be defined as in Theorem 5.6, and set \( \alpha' = \eta\beta \). Then, as in the proof of Theorem 5.6, we have \( \alpha \leq \alpha' \) and \( r_{\alpha'} = \hat{R} \) by (5.16). By Lemma 2.2(iii) and (2.7), it follows that

\[
  r_{\alpha}^* \leq r_{\alpha'}^* \leq r_{\alpha'} = \hat{R}.
\]

Thus, by the assumptions, \( F' \) satisfies the \( L \)-average Lipschitz condition on \( B(x_0, r_{\alpha}^*) \).

On the other hand, noting that

\[
  \frac{4 + 9\eta\beta - 3\sqrt{\eta\beta(9\eta\beta + 8)}}{4\gamma} < \frac{1 + 2\eta\beta - 2\sqrt{\eta\beta(1 + \eta\beta)}}{\gamma},
\]

(5.40)
we see that (5.39) implies (5.24). Therefore, one can apply Theorem 5.6 to conclude that the sequence \( \{x_n\} \) converges to a solution \( x^\ast \) of (1.1) and

\[
\|x_{n+1} - x_n\| \leq q_\alpha^{n-1} \|x_n - x_{n-1}\| \quad \text{for all } n = 1, 2, \ldots.
\]

(5.41)

It remains to show that \( q_\alpha \leq \frac{1}{2} \). To do this we need to emphasize the dependence on the parameters, and so we write \( q(\alpha, \xi) \) for \( q_\alpha \) defined by (5.20) as before. Note that, by (5.27) the right-hand-side member of the inequality (5.40) is simply \( b_\alpha' \), while the left-hand-side member majorizes \( \xi \) by (5.39). It follows from the monotonicity of \( q(\cdot, \cdot) \) established in Lemma 5.5 that

\[
q(\alpha, \xi) \leq q(\alpha', \xi) \leq q \left( \alpha', \frac{4 + 9\eta\beta - 3\sqrt{\eta\beta(9\eta\beta + 8)}}{4\gamma} \right) = \frac{1}{2},
\]

where the last equality can be verified elementarily. This completes the proof. \( \square \)

Similar to the above proof, we can use Theorem 5.7 in place of Theorem 5.6 to verify the following result.

**Theorem 5.11.** Let \( \eta \in [1, +\infty), \Delta \in (0, +\infty] \), and let \( C \) be a cone. Let \( x_0 \in \mathbb{R}^v \) such that \( T_{x_0} \) carries \( \mathbb{R}^v \) onto \( \mathbb{R}^m \). Let \( \xi = \eta\|T_{x_0}^{-1}\|d(F(x_0), C) \) and

\[
\tilde{R} = \left( 1 - \sqrt{\frac{\eta\|T_{x_0}^{-1}\|}{1 + \eta\|T_{x_0}^{-1}\|}} \right) \frac{1}{\gamma}.
\]

Suppose that \( F' \) satisfies the L-average Lipschitz condition on \( B(x_0, \tilde{R}) \) and that

\[
\xi \leq \min \left\{ \frac{4 + 9\eta\|T_{x_0}^{-1}\| - 3\sqrt{\eta\|T_{x_0}^{-1}\|}(9\eta\|T_{x_0}^{-1}\| + 8)}{4\gamma}, \Delta \right\}.
\]

(5.42)

Then, \( x_0 \) is an \( (\eta, \Delta) \)-approximate solution of (1.1).

**6. Examples.** Let us begin with a simple example demonstrating a quasi-regular point which is not a regular point.

**Example 6.1.** Consider the operator \( F \) from \( \mathbb{R}^2 \) to \( \mathbb{R}^2 \) defined by

\[
F(x) = \begin{pmatrix} 1 - t_1 + t_2 + t_2^2 \\ 1 - t_1 + t_2 \end{pmatrix} \quad \text{for each } x = (t_1, t_2) \in \mathbb{R}^2,
\]

where \( \mathbb{R}^2 \) is endowed with the \( l_1 \)-norm. Let \( x_0 = 0 \in \mathbb{R}^2 \) and \( C = \{0\} \subseteq \mathbb{R}^2 \). Then

\[
F'(x) = \begin{pmatrix} -1 + 2t_1 & 1 \\ -t_1 & 1 \end{pmatrix} \quad \text{for each } x = (t_1, t_2) \in \mathbb{R}^2;
\]

in particular, \( F(x_0) = (1, 1) \) and

\[
F'(x_0) = \begin{pmatrix} -1 & 1 \\ -1 & 1 \end{pmatrix}.
\]

Thus \( x_0 \) does not satisfy (3.12). Moreover,

\[
\ker F'(x_0) \cap (C - F(x_0)) = \{(t, t) : t \geq 0\} \neq \{0\}.
\]
and hence \( x_0 \) is not a regular point of the inclusion (3.1). In view of the definition of \( \mathcal{D}(x) \) in (3.2), we have that, for \( x = (t_1, t_2) \in \mathbb{R}^2 \),

\[
\mathcal{D}(x) = \begin{cases} \{(t_1, -1 + \frac{t}{2} - t_2)\}, & t_1 \neq 0, \\ \{(d, d_1 - 1 - t_2) : d_1 \in \mathbb{R}\}, & t_1 = 0 \end{cases}
\]

(note that \( F'(x) \) is of full rank if and only if \( t_1 \neq 0 \)). Therefore,

\[
d(0, \mathcal{D}(x)) \leq 1 + |t_1| + |t_2| = 1 + \|x\| \quad \text{for each} \quad x = (t_1, t_2) \in \mathbb{R}^2
\]

and

\[
d(F(x), C) = |1 - t_1 + t_2 + t_1^2| + |1 - t_1 + t_2| \geq 1 - \|x\| \quad \text{for each} \quad x = (t_1, t_2) \in B(x_0, 1).
\]

This implies that

\[
d(0, \mathcal{D}(x)) \leq \beta(\|x - x_0\|) d(F(x), C) \quad \text{for each} \quad x = (t_1, t_2) \in B(x_0, 1),
\]

where \( \beta(t) = \frac{1 + t}{1 + t} \) for each \( t \in [0, 1) \). Thus, \( x_0 \) is a quasi-regular point with quasi-regular radius \( r_{x_0} \geq 1 \). In fact, \( r_{x_0} = 1 \) because

\[
\lim_{t_1 \to 0^+} \frac{d(0, \mathcal{D}(x))}{d(F(x), C)} = \lim_{t_1 \to 0^+} \frac{1}{t_1} = +\infty
\]

as \( x \) goes to \((0, -1)\) on the radial \( l : 1 - t_1 + t_2 = 0, t_1 \geq 0 \).

Next we give a few examples to illustrate some situations where our results are applicable but not the earlier results in the literature. For the following examples, recall that \( C \) is defined by (1.3) and we take

\[
\eta = 1 \quad \text{and} \quad \Delta = +\infty.
\]

Regarding the convergence issue of Gauss–Newton methods, the advantage of considering Wang’s \( L \)-average Lipschitz condition rather than the classical Lipschitz condition is shown in the following example, for which Theorem 5.7 is applicable but not Theorem 5.3.

**Example 6.2.** Let \( m = n = 1 \) and \( h \) be defined by

\[
h(y) = \begin{cases} 0, & y \leq 0, \\ y, & y \geq 0. \end{cases}
\]

Let \( \tau \) be a constant satisfying

\[
10\sqrt{2} - 14 < \tau < 3 - 2\sqrt{2},
\]

and define

\[
F(x) = \begin{cases} \tau - x + \frac{x^2}{1 - x}, & x \leq \frac{1}{2}, \\ \tau - \frac{1}{2} + 2x^2, & x \geq \frac{1}{2}. \end{cases}
\]

Then \( C = (-\infty, 0] \),

\[
F'(x) = \begin{cases} -2 + \frac{1}{(1-x)^2}, & x \leq \frac{1}{2}, \\ 4x, & x \geq \frac{1}{2}. \end{cases}
\]
and

\[(6.4)\]
\[F''(x) = \begin{cases} 
\frac{2}{(1-x)^2}, & x < \frac{1}{2}, \\
4, & x > \frac{1}{2}.
\end{cases}\]

Let \(\gamma = 1\), and let \(L\) be defined as in (5.15), that is

\[(6.5)\]
\[L(u) = \frac{2}{(1-u)^3} \quad \text{for each } u \text{ with } 0 \leq u < 1.\]

Then

\[(6.6)\]
\[L(u) < L(v) \quad \text{whenever } 0 \leq u < v < 1.\]

It follows from (6.4) that

\[(6.7)\]
\[\sup \{F''(x) : x \in [-r, r] \setminus \{1/2\} \} = \begin{cases} 
16, & r \geq \frac{1}{2}, \\
\frac{2}{(1-r)^2}, & 0 < r \leq \frac{1}{2}.
\end{cases}\]

and that

\[(6.8)\]
\[0 < F''(u) \leq F''(|u|) \leq L(|u|) \quad \text{whenever } 1/2 \neq u < 1.\]

Let \(x_0 = 0\). Then, for all \(x, x' \in \mathcal{B}(x_0, 1)\) with \(|x'| + |x - x'| < 1\), it follows from (6.6) and (6.8) that

\[(6.9)\]
\[|F'(x) - F'(x')| = |x - x'| \int_0^1 F''(x' + t(x - x'))dt \leq |x - x'| \int_0^1 L(|x'| + t|x - x'|)dt.\]

Thus \(F'\) satisfies the \(L\)-average Lipschitz condition on \(\mathcal{B}(x_0, 1)\) with \(L\) defined by (6.5). Note that \(T_{x_0}\) carries \(\mathbb{R}\) onto \(\mathbb{R}\) and \(\|T_{x_0}^{-1}\| = 1\) as \(F'(x_0) = -1\). Let \(\xi\) be defined as in Theorems 5.3 and 5.7. Since \(F(x_0) = \tau\) and by (6.2), we have

\[(6.10)\]
\[\xi = \|T_{x_0}^{-1}\|d(F(x_0), C) = \tau < 3 - 2\sqrt{2}.\]

Thus (5.36) is satisfied. Recalling the definitions of \(\alpha\) and \(r_*^\alpha\) in Theorem 5.7, we have that \(\alpha = 1\) and

\[r_*^\alpha = \frac{1 + \xi - \sqrt{(1 + \xi)^2 - 8\xi}}{4} \leq \frac{1 + \xi}{4} \leq \frac{1 + 3 - 2\sqrt{2}}{4} < 1.\]

Therefore Theorem 5.7 is applicable with initial point \(x_0\). We show next that Theorem 5.3 is not applicable here. In fact, by (6.7), one has that, for any \(r > 0\), \(F'\) is also Lipschitz continuous on \(\mathcal{B}(x_0, r)\) with the (least) Lipschitz constant \(L_r\) given by

\[(6.11)\]
\[L_r = \begin{cases} 
\frac{2}{(1-r)^2}, & r \leq \frac{1}{2}, \\
16, & r \geq \frac{1}{2}.
\end{cases}\]

Suppose that there are \(\xi, L,\) and \(R^*\) satisfying the assumptions stated in Theorem 5.3. For simplicity of notation we write \(r\) for \(R^*\). Then by the least property of \(L_r\), (5.12), (5.14), and by a similar argument as for (6.10), we have

\[(6.12)\]
\[L \geq L_r,\]

\[(6.13)\]
\[r = \frac{1 - \sqrt{1 - 2L\xi}}{L}.\]
and

(6.14) \[ \tau = \xi \leq \frac{1}{2L} \leq \frac{1}{2L_r}. \]

Since \( \tau > 10\sqrt{2} - 14 > \frac{1}{2L_r} \), we have from (6.14) that \( L_r < 16 \), and it follows from (6.11) that \( r < 1/2 \) and hence \( L_r = \frac{2}{(1-r)^2} \geq 2 \). Consequently, by (6.12) and (6.13), we have

(6.15) \[ \tau = \xi = r - \frac{Lr^2}{2} \leq r - \frac{Lr^2}{2} \leq r - r^2. \]

Combining this with (6.14) and (6.11), we have that

(6.16) \[ \tau \leq \min \left\{ \frac{(1-r)^3}{4}, r - r^2 \right\}. \]

Note that the function \( r \mapsto \frac{(1-r)^3}{4} \) is decreasing and \( r \mapsto r - r^2 \) increasing on \([0, 1/2]\). Hence

(6.17) \[ \tau \leq \min \left\{ \frac{(1-r)^3}{4}, r - r^2 \right\} = r_0 - r_0^2 = 10\sqrt{2} - 14, \]

where \( r_0 = 3 - 2\sqrt{2} \) is the least positive root of equation \( \frac{(1-r)^3}{4} = r - r^2 \). However, (6.17) contradicts (6.2), and therefore Theorem 5.3 is not applicable to \( x_0 \).

Even when initial point \( x_0 \) is regular, the advantage to considering the quasi-regularity bound functions rather than a constant \( \beta \) with the property stated in Proposition 3.3 is shown in the following example, for which Theorem 5.1 (and hence results in [4, 13]) are not applicable while Theorem 5.3 is applicable, which is based on the quasi-regular bound function \( \beta_{x_0} \) satisfying (3.14) rather than the quasi-regular bound constant \( \beta \) given by Proposition 3.3.

Example 6.3. Let \( m = n = 1 \) and \( h \) be defined by

\[ h(y) = |y| \quad \text{for each } y \in \mathbb{R}. \]

Then \( C = \{0\} \). Let \( \frac{\sqrt{3}-1}{4} < \tau \leq \frac{1}{4} \) and define

\[ F(x) = \tau - x + x^2 \quad \text{for each } x \in \mathbb{R}. \]

Then

\[ F'(x) = -1 + 2x \quad \text{for each } x \in \mathbb{R}; \]

hence \( F' \) is Lipschitz continuous with the modular \( L = 2 \). Let \( x_0 = 0 \). It is clear that \( T_{x_0} \) carries \( \mathbb{R} \) onto \( \mathbb{R} \) and \( \|T_{x_0}^{-1}\| = 1 \) as \( F'(x_0) = -1 \). Since

(6.18) \[ \|T_{x_0}^{-1}\|d(F(x_0), C) = \tau \leq \frac{1}{4}, \]

Theorem 5.3 is applicable with initial point \( x_0 = 0 \). Below we shall show that Theorem 5.1 is not applicable. Suppose, on the contrary, that there exist \( r > 0 \) and \( \beta > 0 \) satisfying the assumptions stated in Theorem 5.1 for \( x_0 \). Then

(6.19) \[ D(x) \text{ is nonempty and } d(0, D(x)) \leq \beta d(F(x), C) \quad \text{for each } x \in B(x_0, r), \]
\begin{equation}
\label{6.20}
r \geq \frac{1 + 2\beta \xi - \sqrt{1 - (2\beta \xi)^2}}{2\beta},
\end{equation}

and

\begin{equation}
\label{6.21}
\beta \tau = \xi \leq \frac{1}{2\beta}.
\end{equation}

By definition, it is easy to see that, for each \(x \in \mathbb{R}\),

\begin{equation}
\label{6.22}
D(x) = \begin{cases}
\{-F'(x)^{-1}F(x)\}, & x \neq \frac{1}{2}, \\
\emptyset, & x = \frac{1}{2},
\end{cases}
\end{equation}

and it follows from (6.19) that \(r \leq \frac{1}{2}\) and, for each \(x \in B(x_0, r)\),

\begin{equation}
\label{6.23}
d(0, D(x)) = |F'(x)^{-1}F(x)| = \frac{1}{1 - 2|x|} |F(x)| = \frac{1}{1 - 2|x|} d(F(x), C).
\end{equation}

By (6.19) this implies that

\begin{equation}
\label{6.24}
\frac{1}{1 - 2|x|} \leq \beta \quad \text{for each } x \in B(x_0, r).
\end{equation}

Considering \(x_0 = 0\), this implies \(\frac{1}{1 - 2r} \leq \beta\); that is,

\begin{equation}
\label{6.25}
2\beta r \leq \beta - 1.
\end{equation}

It follows from (6.20) that

\begin{equation}
\label{6.26}
1 + 2\beta \xi - \sqrt{1 - (2\beta \xi)^2} \leq \beta - 1,
\end{equation}

or equivalently,

\begin{equation}
\label{6.27}
((2\xi - 1)^2 + (2\xi)^2)\beta^2 + 4(2\xi - 1)\beta + 3 \leq 0.
\end{equation}

Hence

\begin{equation}
\label{6.28}
(4(2\xi - 1)^2 - 4 \cdot 3((2\xi - 1)^2 + (2\xi)^2) \geq 0,
\end{equation}

which implies that \(\xi \leq \frac{\sqrt{3} - 1}{4}\). This contradicts the assumption that \(\tau > \frac{\sqrt{3} - 1}{4}\) because \(\xi = \beta \tau \geq \tau\) by (6.21) and (6.24).

We remark that, on one hand, the results in section 5 cover (and improve) the cases considered by Burke and Ferris and by Robinson (the initial points are regular in [4, 18]), and, on the other hand, there are examples of quasi-regular but not regular points \(x_0\) for which Theorem 4.1 is applicable.

Example 6.4. Let \(m = n = 3\). To ease our computation, let \(\mathbb{R}^3\) be endowed with the \(l_1\)-norm. Let \(h\) be defined by

\[ h(x) = \chi(t_1) + \chi(t_2) + \left| t_3 - t_1 - t_2 - \frac{1}{8} \right| \quad \text{for each } x = (t_1, t_2, t_3) \in \mathbb{R}^3, \]

where \(\chi(t)\) is a real-valued function on \(\mathbb{R}\) defined by

\[ \chi(t) = \begin{cases}
-1 - t, & t \leq -1, \\
0, & -1 \leq t \leq 0, \\
t, & t \geq 0.
\end{cases} \]
Define

(6.29) \[ A = \{(c_1, c_2, c_3) : c_3 = c_1 + c_2\} \]

and let \( F : \mathbb{R}^3 \to \mathbb{R}^3 \) be defined by

(6.30) \[
F(x) = \begin{pmatrix}
\frac{1}{16} - t_1 + t_1^2 + t_2 + t_3 \\
\frac{1}{16} + t_1 - t_2 + t_2^2 + t_3 \\
t_1^2 + t_2^2 + 2t_3
\end{pmatrix}
\]

for each \( x = (t_1, t_2, t_3) \in \mathbb{R}^3 \).

Then

(6.31) \[ C = \{(c_1, c_2, c_3) : c_1, c_2 \in [-1, 0], c_3 = c_1 + c_2 + \frac{1}{8}\} \]

(6.32) \[
C - F(x) \text{ is contained in } A,
\]

(6.33) \[
F'(x) = \begin{pmatrix}
-1 + 2t_1 & 1 & 1 \\
1 & -1 + 2t_2 & 1 \\
2t_1 & 2t_2 & 2
\end{pmatrix}
\]

for each \( x = (t_1, t_2, t_3) \in \mathbb{R}^3 \),

and hence

(6.34) \[ C - F(x) \text{ is contained in } A = \{F'(x)d : d \in \mathbb{R}^3\} \text{ for each } x \in \mathbb{R}^3. \]

In particular, for \( x_0 = 0 \), we have that

(6.35) \[
F'(x_0) = \begin{pmatrix}
-1 & 1 & 1 \\
1 & -1 & 1 \\
0 & 0 & 2
\end{pmatrix},
\]

and hence

(6.36) \[
\ker F'(x_0) = \{(t, t, 0) : t \in \mathbb{R}\}.
\]

Since \( F(x_0) = (\frac{1}{16}, \frac{1}{16}, 0) \), one has that

(6.37) \[
\ker F'(x_0) \cap (C - F(x_0))^{\oplus} = \{(t, t, 0) : t \geq 0\};
\]

hence \( x_0 \) is not a regular point of (3.1), and the condition of Robinson is not satisfied (see Proposition 3.7). Below we shall show that \( x_0 \) is a quasi-regular point with the quasi-regular radius \( r_{x_0} \) and the quasi-regular bound function \( \beta_{x_0} \) satisfying respectively

(6.38) \[
\begin{align*}
 r_{x_0} & \geq \frac{3}{4} \quad \text{and} \quad \beta_{x_0}(t) \leq \frac{2}{3 - 4t} \quad \text{for each } t \in \left[0, \frac{3}{4}\right].
\end{align*}
\]

To do this, we note first that \( F' \) satisfies the \( L \)-average Lipschitz condition on \( \mathbb{R}^3 \) with \( L = 2 \),

(6.39) \[
\|F'(x) - F'(y)\| \leq 2\|x - y\| \quad \text{for each } x, y \in \mathbb{R}^3,
\]

and the rank of \( F'(x) \) is given by

(6.40) \[
\text{rank } F'(x) = 2 \quad \text{for each } x \in \mathbb{R}^3.
\]
Since
\[ F'(x) = F'(x_0) + F'(x) - F'(x_0) \quad \text{and} \quad \| F'(x) - F'(x_0) \| \leq 2 \| x - x_0 \|, \]
it follows from the perturbation property of matrices (cf. [27, 30]) that
\[
\| F'(x)^\dagger \| \leq \frac{\| F'(x_0)^\dagger \|}{1 - 2 \| x - x_0 \| \| F'(x_0)^\dagger \|}
\]
holds for each \( x \in \mathbb{R}^3 \) with \( 2 \| x - x_0 \| \| F'(x_0)^\dagger \| < 1 \), where \( A^\dagger \) denotes the Moore–Penrose generalized inverse of the matrix \( A \) (cf. [27, 30]). By (6.35), one has that
\[
\| F'(x_0)^\dagger \| = \frac{2}{3}
\]
This together with (6.41) implies that
\[
\| F'(x)^\dagger \| \leq \frac{2}{3 - 4 \| x - x_0 \|} \quad \text{for each} \quad x \in B \left( x_0, \frac{3}{4} \right).
\]
On the other hand, by (6.33) and (3.2), we have
\[
D(x) = F'(x)^\dagger (C - F(x)) \quad \text{for each} \quad x \in \mathbb{R}^3
\]
and, consequently, for each \( x \in B \left( x_0, \frac{3}{4} \right) \),
\[
d(0, D(x)) \leq \| F'(x)^\dagger \| d(F(x), C) \leq \frac{2}{3 - 4 \| x - x_0 \|} d(F(x), C).
\]
This shows that \( x_0 \) is a quasi-regular point with the quasi-regular radius \( r_{x_0} \) and the quasi-regular bound function \( \beta_{x_0} \) satisfying (6.38). Let \( r = \frac{3}{4} \). Recalling (4.2) and (6.1), it follows from (6.38) that
\[
\alpha_0(r) = \sup \left\{ \frac{\beta(t)}{\beta(t)2t + 1} : \xi \leq t < r \right\} = \frac{2}{3},
\]
where \( \beta(t) := \frac{2}{3 - 4t} \) for each \( t \in [0, \frac{3}{4}) \). Thus taking \( \alpha = \frac{2}{3} \) in (2.1), we get that
\[
r_\alpha = \frac{3}{4} \quad \text{and} \quad b_\alpha = \frac{3}{8}.
\]
By (4.1) and (6.38),
\[
\xi = \beta_{x_0}(0)d(F(x_0), C) \leq \beta(0)\| F(x_0) - c_0 \| = \frac{1}{6},
\]
where \( c_0 = (0, 0, \frac{1}{8}) \). It follows that (4.4) is satisfied. Hence Theorem 4.1 is applicable with initial point \( x_0 \) even though it is not a regular point.
7. Conclusion. In connection with inclusion problem (1.2) and for a given point \( x_0 \) we introduce two new notions: (a) the \( L \)-average Lipschitz condition for \( F' \) and (b) quasi regularity (with the associate quasi-regular radius \( r_{x_0} \) and quasi-regular bound function \( \beta_{x_0} \)). The notion (a) extends the classical Lipschitz condition and Smale’s condition, and notion (b) extends the regularity. When Robinson’s condition (3.12) is satisfied, \( x_0 \) is shown to be a regular point, and the associate quasi-regular radius \( r_{x_0} \) as well as the associate quasi-regular bound function \( \beta_{x_0} \) are estimated if in addition \( F' \) satisfies (a) with suitable \( L \). We provide sufficient conditions for convergence results with a quasi-regular initial point \( x_0 \) in the Gauss–Newton method for the convex composition optimization problem (1.1) with \( C \) given to be the set of all minimizers of a convex function \( h \). These conditions are given in terms of \( r_{x_0} \), \( \beta_{x_0} \), and \( L \) in (a). Examples are given to show that the new concept and results are nontrivial extensions of the existing ones.

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